

```

////////// CW Decoder //////////////////////////////////////////////////////////////////
// CW Decoder made by Hjalmar Skovholm Hansen OZ1JHM VER 1.01      //
// Feel free to change, copy or what ever you like but respect      //
// that license is http://www.gnu.org/copyleft/gpl.html           //
// Discuss and give great ideas on                                //
// https://groups.yahoo.com/neo/groups/oz1jhm/conversations/messages //
////////////////////////////////////////////////////////////////

////////// Goertzel algorithm //////////////////////////////////////////////////////////////////
// Read more here http://en.wikipedia.org/wiki/Goertzel_algorithm   //
// if you want to know about FFT the http://www.dspguide.com/pdfbook.htm //
////////////////////////////////////////////////////////////////

#include <LiquidCrystal.h>

////////// LCD panel pins //////////////////////////////////////////////////////////////////
// select the pins used on the LCD panel   /
// LiquidCrystal lcd(RS, E, D4, D5, D6, D7) //
////////////////////////////////////////////////////////////////

LiquidCrystal lcd(12, 11, 5, 4, 3, 2);

const int columns = 20; // have to be 16 or 20
const int rows = 4; // have to be 2 or 4

int lcdindex = 0;
int line1[columns];
int line2[columns];

////////// Special letters //////////////////////////////////////////////////////////////////
// Define 8 specials letters //
////////////////////////////////////////////////////////////////

byte U_umlaut[8] = {B01010,B00000,B10001,B10001,B10001,B10001,B01110,B00000}; // 'Ü'
byte O_umlaut[8] = {B01010,B00000,B01110,B10001,B10001,B10001,B01110,B00000}; // 'Ö'
byte A_umlaut[8] = {B01010,B00000,B01110,B10001,B11111,B10001,B10001,B00000}; // 'Ä'
byte AE_capital[8] = {B01111,B10100,B10100,B11110,B10100,B10100,B10111,B00000}; // 'Æ'
byte OE_capital[8] = {B00001,B01110,B10011,B10101,B11001,B01110,B10000,B00000}; // 'Ø'
byte fullblock[8] = {B11111,B11111,B11111,B11111,B11111,B11111,B11111,B11111};
byte AA_capital[8] = {B00100,B00000,B01110,B10001,B11111,B10001,B10001,B00000}; // 'Å'
byte emtyblock[8] = {B00000,B00000,B00000,B00000,B00000,B00000,B00000,B00000};

int audioInPin = A1;
int audioOutPin = 10;
int ledPin = 13;

float magnitude ;
int magnitudelimit = 100;
int magnitudelimit_low = 100;
int realstate = LOW;
int realstatebefore = LOW;
int filteredstate = LOW;
int filteredstatebefore = LOW;

////////////////////////////////////////////////////////////////
// The sampling frq will be 8928 on a 16 mhz          //
// without any prescaler etc                         //
// because we need the tone in the center of the bins //
// you can set the tone to 496, 558, 744 or 992        //
// then n the number of samples which give the bandwidth //

```

```

// can be (8928 / tone) * 1 or 2 or 3 or 4 etc          //
// init is 8928/558 = 16 *4 = 64 samples              //
// try to take n = 96 or 128 ;o)                      //
// 48 will give you a bandwidth around 186 hz          //
// 64 will give you a bandwidth around 140 hz          //
// 96 will give you a bandwidth around 94 hz           //
// 128 will give you a bandwidth around 70 hz           //
// BUT remember that high n take a lot of time         //
// so you have to find the compromice - i use 48        //
////////////////////////////////////////////////////////////////

float coeff;
float Q1 = 0;
float Q2 = 0;
float sine;
float cosine;
float sampling_freq=8928.0;
float target_freq=558.0; // adjust for your needs see above
float n=48.0; // if you change her please change next line also
int testData[48];

////////////////////////////////////////////////////////////////
// Noise Blanker time which //
// shall be computed so      //
// this is initial           //
////////////////////////////////////////////////////////////////
int nbtime = 6; // ms noise blunker

long starttimehigh;
long highduration;
long lasthighduration;
long hightimesavg;
long lowtimesavg;
long startttimelow;
long lowduration;
long laststarttime = 0;

char code[20];
int stop = LOW;
int wpm;

////////////////////////////////////////////////////////////////
// init setup //
////////////////////////////////////////////////////////////////
void setup() {

////////////////////////////////////////////////////////////////
// The basic goertzel calculation //
////////////////////////////////////////////////////////////////
    int k;
    float omega;
    k = (int) (0.5 + ((n * target_freq) / sampling_freq));
    omega = (2.0 * PI * k) / n;
    sine = sin(omega);
    cosine = cos(omega);
    coeff = 2.0 * cosine;

////////////////////////////////////////////////////////////////
// define special characters //
////////////////////////////////////////////////////////////////
    lcd.createChar(0, U_umlaut); // German
    lcd.createChar(1, O_umlaut); // German, Swedish
    lcd.createChar(2, A_umlaut); // German, Swedish
    lcd.createChar(3, AE_capital); // Danish, Norwegian
    lcd.createChar(4, OE_capital); // Danish, Norwegian
    lcd.createChar(5, fullblock);
    lcd.createChar(6, AA_capital); // Danish, Norwegian, Swedish
}

```

```

lcd.createChar(7, emtyblock);
lcd.clear();

Serial.begin(115200);
pinMode(ledPin, OUTPUT);
lcd.begin(columns, rows);
for (int index = 0; index < columns; index++) {
    line1[index] = 32;
    line2[index] = 32;
}

}

///////////
// main loop //
///////////
void loop() {

///////////
// The basic where we get the tone //
///////////

for (char index = 0; index < n; index++)
{
    testData[index] = analogRead(audioInPin);
}
for (char index = 0; index < n; index++){
    float Q0;
    Q0 = coeff * Q1 - Q2 + (float) testData[index];
    Q2 = Q1;
    Q1 = Q0;
}
float magnitudeSquared = (Q1*Q1)+(Q2*Q2)-Q1*Q2*coeff; // we do only need the real
part //
magnitude = sqrt(magnitudeSquared);
Q2 = 0;
Q1 = 0;

//Serial.print(magnitude); Serial.println(); // here you can measure magnitude
for setup..

///////////
// here we will try to set the magnitude limit automatic //
///////////

if (magnitude > magnitudelimit_low){
    magnitudelimit = (magnitudelimit +((magnitude - magnitudelimit)/6)); // moving
average filter
}

if (magnitudelimit < magnitudelimit_low)
    magnitudelimit = magnitudelimit_low;

///////////
// now we check for the magnitude //
///////////

if(magnitude > magnitudelimit*0.6) // just to have some space up
    realstate = HIGH;
else
    realstate = LOW;

///////////
// here we clean up the state with a noise blunker //
///////////

if (realstate != realstatebefore){
    laststarttime = millis();
}

```

```

}

if ((millis()-laststarttime)> nbtime){
    if (realstate != filteredstate){
        filteredstate = realstate;
    }
}

///////////////////////////////
// Then we do want to have some durations on high and low //
///////////////////////////////

if (filteredstate != filteredstatebefore){
    if (filteredstate == HIGH){
        starttimehigh = millis();
        lowduration = (millis() - startttimelow);
    }

    if (filteredstate == LOW){
        startttimelow = millis();
        highduration = (millis() - starttimehigh);
        if (highduration < (2*hightimesavg) || hightimesavg == 0){
            hightimesavg = (highduration+hightimesavg+hightimesavg)/3;
        }
        if (highduration > (5*hightimesavg) ){
            hightimesavg = highduration+hightimesavg; // if speed
decrease fast ..
        }
    }
}

/////////////////////////////
// now we will check which kind of baud we have - dit or dah //
// and what kind of pause we do have 1 - 3 or 7 pause          //
// we think that hightimeavg = 1 bit                           //
/////////////////////////////


if (filteredstate != filteredstatebefore){
    stop = LOW;
    if (filteredstate == LOW){ // we did end a HIGH
        if (highduration < (hightimesavg*2) && highduration > (hightimesavg*0.6)){ /// 0.6
filter out false bits
        strcat(code,".");
        Serial.print(".");
    }
    if (highduration > (hightimesavg*2) && highduration < (hightimesavg*6)){
        strcat(code,"-");
        Serial.print("-");
        wpm = (wpm + (1200/((highduration)/3)))/2; // the most precise we can do
;o)
    }
}

if (filteredstate == HIGH){ // we did end a LOW

    float lacktime = 1;
    if(wpm > 25)lacktime=1.0; /// when high speeds we have to have a little more
pause before new letter or new word
    if(wpm > 30)lacktime=1.2;
    if(wpm > 35)lacktime=1.5;

    if (lowduration > (hightimesavg*(2*lacktime)) && lowduration <
hightimesavg*(5*lacktime)){ // letter space
        docode();
        code[0] = '\0';
        Serial.print("/");
    }
    if (lowduration >= hightimesavg*(5*lacktime)){ // word space
}
}

```

```

        docode();
        code[0] = '\0';
        printascii(32);
        Serial.println();
    }
}

///////////
// write if no more letters //
///////////

if ((millis() - starttimelow) > (highduration * 6) && stop == LOW) {
    docode();
    code[0] = '\0';
    stop = HIGH;
}

///////////
// we will turn on and off the LED //
// and the speaker                      //
///////////

if(filteredstate == HIGH){
    digitalWrite(ledPin, HIGH);
    tone(audioOutPin,target_freq);
}
else{
    digitalWrite(ledPin, LOW);
    noTone(audioOutPin);
}

///////////
// the end of main loop clean up//
/////////
updateinfolinelcd();
realstatebefore = realstate;
lasthighduration = highduration;
filteredstatebefore = filteredstate;
}

///////////
// translate cw code to ascii //
///////////

void docode(){
    if (strcmp(code,".-") == 0) printascii(65);
    if (strcmp(code,"-...") == 0) printascii(66);
    if (strcmp(code,"-.") == 0) printascii(67);
    if (strcmp(code,"..") == 0) printascii(68);
    if (strcmp(code,".") == 0) printascii(69);
    if (strcmp(code,"..-.") == 0) printascii(70);
    if (strcmp(code,"--") == 0) printascii(71);
    if (strcmp(code,"....") == 0) printascii(72);
    if (strcmp(code,"..") == 0) printascii(73);
    if (strcmp(code,"---") == 0) printascii(74);
    if (strcmp(code,".-.") == 0) printascii(75);
    if (strcmp(code,"--") == 0) printascii(76);
    if (strcmp(code,"-..") == 0) printascii(77);
    if (strcmp(code,"-") == 0) printascii(78);
    if (strcmp(code,"---") == 0) printascii(79);
    if (strcmp(code,"...-") == 0) printascii(80);
    if (strcmp(code,"--.-") == 0) printascii(81);
    if (strcmp(code,".-") == 0) printascii(82);
    if (strcmp(code,"...") == 0) printascii(83);
    if (strcmp(code,"-") == 0) printascii(84);
    if (strcmp(code,"..-") == 0) printascii(85);
}

```

```

if (strcmp(code,"...-") == 0) printascii(86);
if (strcmp(code,".--") == 0) printascii(87);
if (strcmp(code,"-..-") == 0) printascii(88);
if (strcmp(code,"-.-.") == 0) printascii(89);
if (strcmp(code,"--..") == 0) printascii(90);

if (strcmp(code,"----") == 0) printascii(49);
if (strcmp(code,"...--") == 0) printascii(50);
if (strcmp(code,"...-") == 0) printascii(51);
if (strcmp(code,"....") == 0) printascii(52);
if (strcmp(code,"-....") == 0) printascii(53);
if (strcmp(code,"-....") == 0) printascii(54);
if (strcmp(code,"--...") == 0) printascii(55);
if (strcmp(code,"---..") == 0) printascii(56);
if (strcmp(code,"----.") == 0) printascii(57);
if (strcmp(code,"-----") == 0) printascii(48);

if (strcmp(code,"...-..") == 0) printascii(63);
if (strcmp(code,".-.-.") == 0) printascii(46);
if (strcmp(code,"--...-") == 0) printascii(44);
if (strcmp(code,"-.-.-") == 0) printascii(33);
if (strcmp(code,".-.-.") == 0) printascii(64);
if (strcmp(code,"----..") == 0) printascii(58);
if (strcmp(code,"-....") == 0) printascii(45);
if (strcmp(code,"-...-") == 0) printascii(47);

if (strcmp(code,"-.-..") == 0) printascii(40);
if (strcmp(code,"-...-") == 0) printascii(41);
if (strcmp(code,"-....") == 0) printascii(95);
if (strcmp(code,"...-.-") == 0) printascii(36);
if (strcmp(code,"...-.-") == 0) printascii(62);
if (strcmp(code,".-.-.") == 0) printascii(60);
if (strcmp(code,"...-..") == 0) printascii(126);
///////////////////
// The specials //
/////////////////
if (strcmp(code,".-.-") == 0) printascii(3);
if (strcmp(code,"---.") == 0) printascii(4);
if (strcmp(code,".-.-.") == 0) printascii(6);

}

///////////////////////////////
// print the ascii code to the lcd //
// one a time so we can generate   //
// special letters               //
///////////////////////////////
void printascii(int asciinumber){

int fail = 0;
if (rows == 4 and colums == 16)fail = -4; // to fix the library problem with 4*16
display http://forum.arduino.cc/index.php/topic,14604.0.html

if (lcdindex > colums-1){
    lcdindex = 0;
    if (rows==4){
        for (int i = 0; i <= colums-1 ; i++){
            lcd.setCursor(i,rows-3);
            lcd.write(line2[i]);
            line2[i]=line1[i];
        }
    }
    for (int i = 0; i <= colums-1 ; i++){
        lcd.setCursor(i+fail,rows-2);
        lcd.write(line1[i]);
        lcd.setCursor(i+fail,rows-1);
        lcd.write(32);
    }
}

```

```
}

line1[lcdindex]=asciinumber;
lcd.setCursor(lcdindex+fail,rows-1);
lcd.write(asciinumber);
lcdindex += 1;
}

void updateinfolinelcd(){
///////////////////////////////
// here we update the upper line //
// with the speed.               //
///////////////////////////////

int place;
if (rows == 4){
    place = columns/2;
} else{
    place = 2;
}
if (wpm<10) {
    lcd.setCursor((place)-2,0);
    lcd.print("0");
    lcd.setCursor((place)-1,0);
    lcd.print(wpm);
    lcd.setCursor((place),0);
    lcd.print(" WPM");
}
else{
    lcd.setCursor((place)-2,0);
    lcd.print(wpm);
    lcd.setCursor((place),0);
    lcd.print(" WPM ");
}
}

}
```